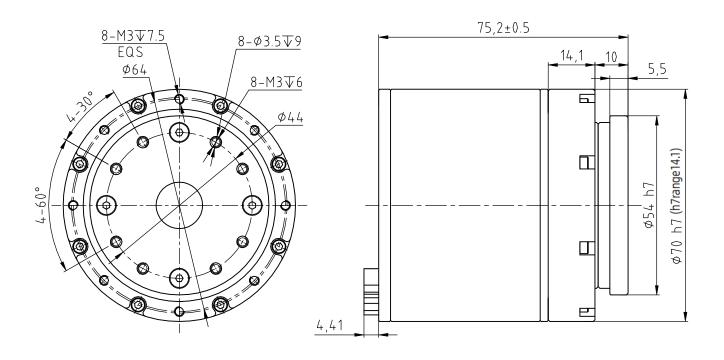
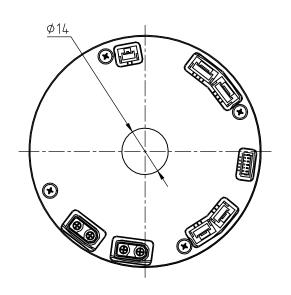
Sign





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GJ-DW-ME-0007

⑤ Lallfuall Drflv。 新江来福谐波传动股份有限公司 <u>B2</u> Si gn

	Module S	ignal Definition							
Pin NO.	Signal Name	Remarks							
A1/B1	VBUS+	VBUS+ Bus Power Input/Output Positive Terminal							
A2/B2	VBUS-	VBUS- Bus Power Input/Output Negative Terminal							
D1	BAT+	BAT+ Multiturn Encoder Backup Battery Positive Terminal							
D2	BAT-	BAT- Multiturn Encoder Backup Battery Negative Terminal							
F1	E1_RX+	E1_RX+ EtherCAT Output Receive Positive Terminal							
F2	E1_RX-	E1_RX- EtherCAT Output Receive Negative Terminal							
F3	E1_TX+	E1_TX+ EtherCAT Output Transmit Positive Terminal							
F4	E1_TX-	E1_TX- EtherCAT Output Transmit Negative Terminal							
G1	E0_RX+	E0_RX+ EtherCAT Input Receive Positive Terminal							
G2	EO_RX-	E0_RX- EtherCAT Input Receive Negative Terminal							
G3	E0_TX+	E0_TX+ EtherCAT Input Transmit Positive Terminal							
G4	EO_TX-	E0_TX- EtherCAT Input Transmit Negative Terminal							
J1/K1	RS485_A	RS485_A RS485 Bus A Terminal							
J2/K2	RS485_GND	RS485_GND RS485 Bus Ground							
J3/K3	RS485_B	RS485_B RS485 Bus B Terminal							

Technical requirements:
1. Insulation resistance (DC500V) > 500M , insulation withstand voltage AC500V (1 minute), less than 5mA;
2. Motor-side encoder resolution: 16-bit multi-turn, 17-bit single-turn;
Encoder resolution at reducer end: 17-bit singleturn;
3. Bus protocol: EtherCAT.
4. Appearance without obvious burrs, scratches, bumps and other defects;
5. Operating temperature: -25-55;
6. Unidirectional positioning accuracy: 60Arc sec, repeat positioning accuracy: 20Arc sec.

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Module Data																		
Ratio	Rated Torque (Nm)	Permissible peak torque at start/stop (Nm)		(rnm)	Max.Speed (rpm)	Rated Current (A)	Max.Current (A)	Tq·Constant (Nm/Arms)	Inertia Moment (kg·mm²)	Weight (kg)	标记	处数	更改内容	签字	当 月 期	Rotary	actuator	-
51	9	23	46	58. 8	107.8	3. 23	8. 25	2. 79			设审	计核]		
81	14	30	61	37	67. 9	3. 16	6. 77	4. 43	61. 2	1.01	批	准				客户图样标记	重量(kg) 比	例
101	14	36	70	29. 7	54. 5	2. 53	6. 52	5. 52	01. 2	1.01	工艺					1	1:	:1
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